

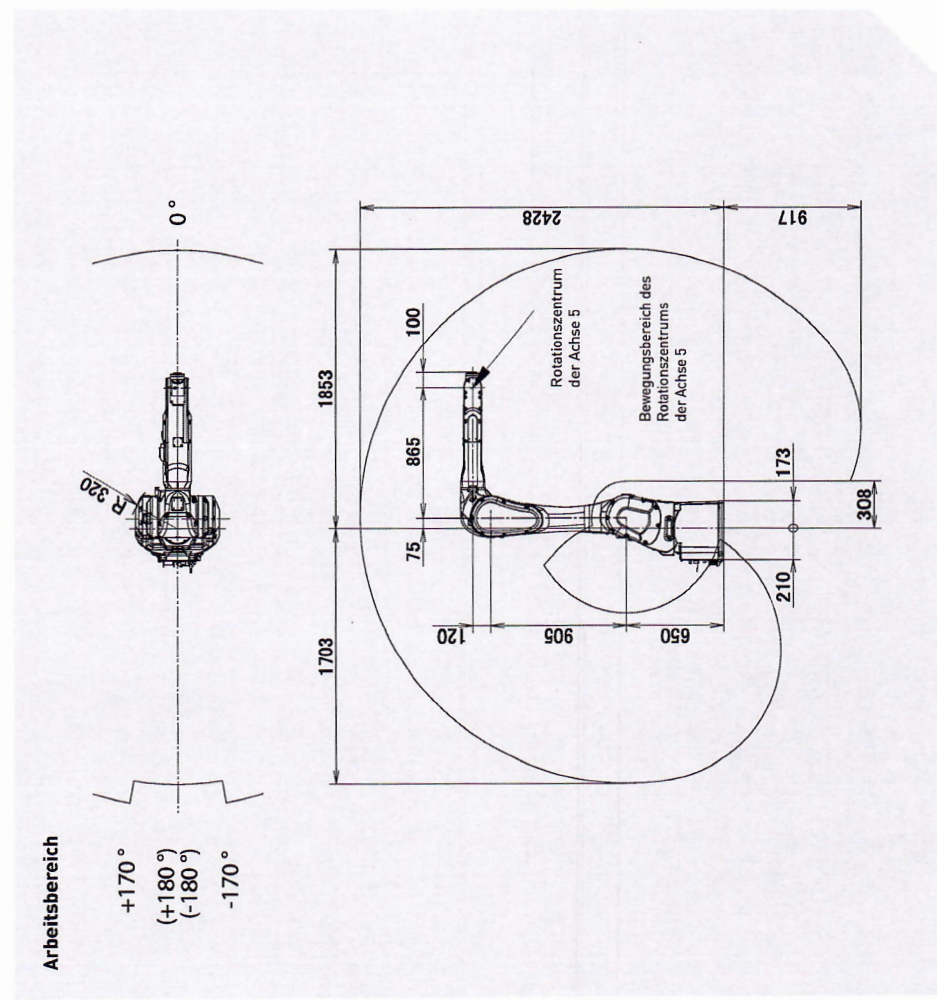
M-20iB/25C

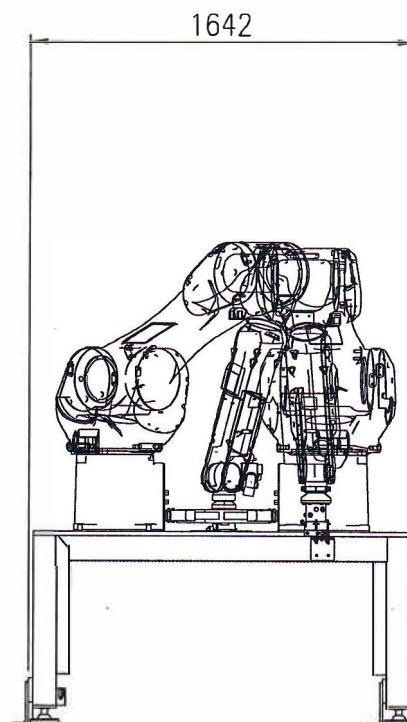
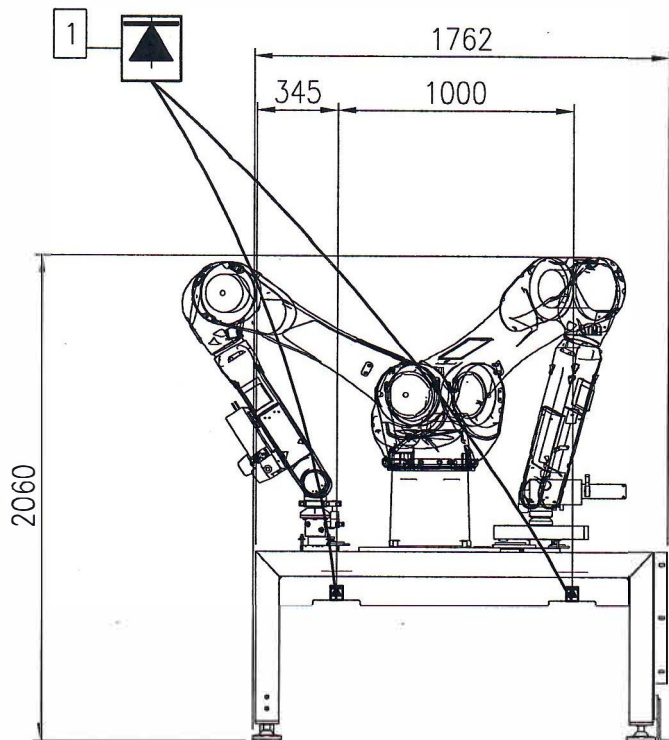
Max. Gewicht am Handgelenk: **25 kg**

Max. Reichweite: **1853 mm**

Achszahl	Wiederholgenauigkeit (mm)	Gewicht der Mechanik (kg)	Arbeitsbereich (°)						Achsgeschwindigkeit (°/s)				A4 Moment/Trägheit (Nm/kgm²)	A5 Moment/Trägheit (Nm/kgm²)	A6 Moment/Trägheit (Nm/kgm²)
			A1	A2	A3	A4	A5	A6	A1	A2	A3	A4	A5	A6	
6	± 0.023*	210	340(360)	240	303	400	290	540	205	205	260	415	415	880	31/1.2

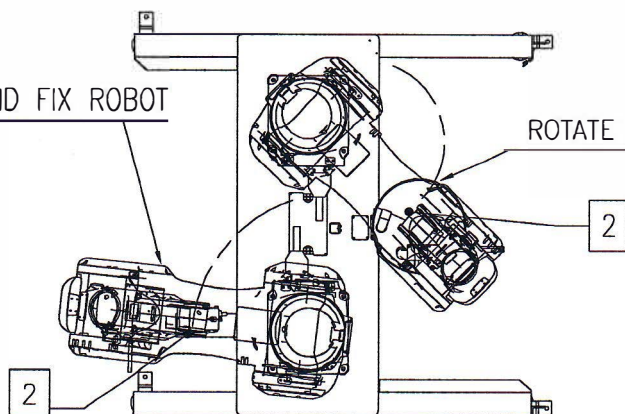
Robot		M-20iB/25C
Roboter aufstellmaße [mm]		383 x 343
Bodenmontage		•
Deckenmontage		•
Wandmontage		•
Steuerung		R-30iB Plus
Schaltschranktyp Open Air		-
Schaltschranktyp Mate		o
Schaltschranktyp A		•
Schaltschranktyp B		o
iPendant Touch (Standard)		•
Stromanschlüsse		
Elektrische Spannung 50/60Hz, 3 Phasen [V]		380-575
Elektrische Spannung 50/60Hz, 1 Phase [V]		-
Durchschnittliche Leistung [kW]		1
Integrierte Funktionen		
Integrierte Signale am Oberarm In / Out (Haltesignale)		8/2
Integrierte Luftzufuhr		1
Umgebung		
Schallleistungspegel [dB]		< 70
Umgebungstemperatur [° C]		0-45
Schutzart		
Mechanik Standard/optional		IP67
Handgelenk & A3 Arm Standard/optional		IP67
Luftreinheitsklasse		
Reinraumklasse gemäß ISO 14644-1		ISO Klasse 5





ROTATE AND FIX ROBOT

ROTATE AND FIX ROBOT



2	B798598	LIFTING TOOL		2
1	5450058	ADHESIVE RECTANGU.PL. ISO7000(0542)65x45		2
ITEM	CODE	COMPONENT DENOMINATION	TRACEABILITY CODE	Q.TY



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COUNTRY

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Serra G.

DRAWN UP

Mezzetti D.

DATE

08/08/2022

SHEET

1/3

SERIAL No.

7995



SCALE

1:20

DRAWING No.

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REV

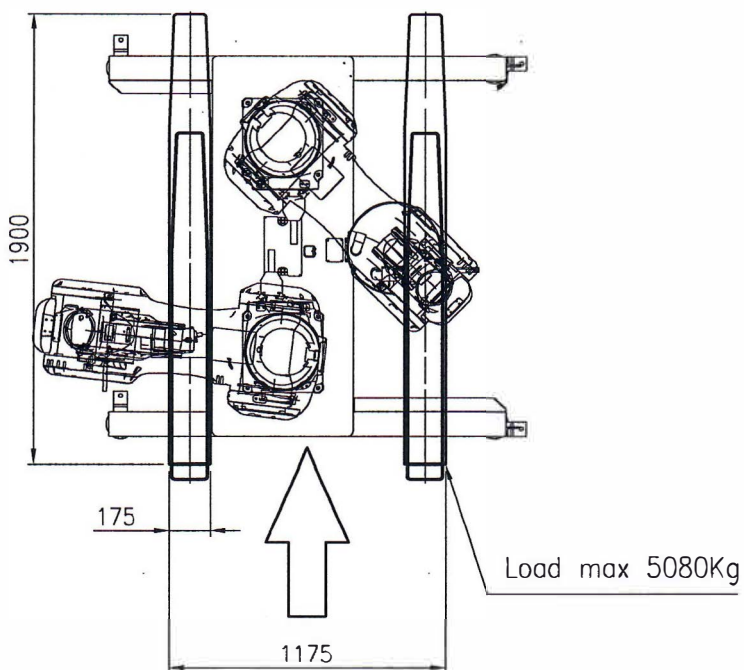
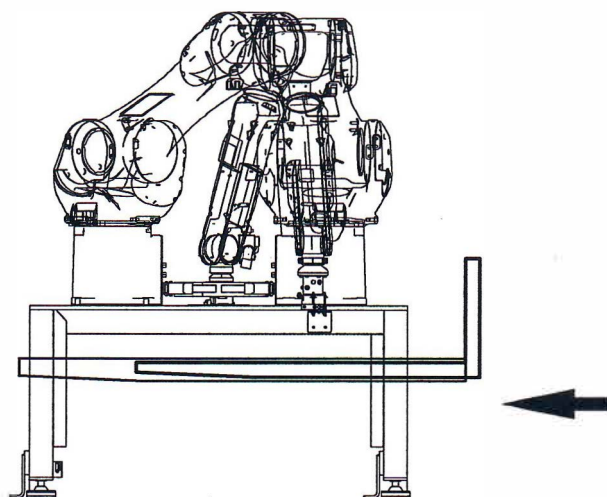
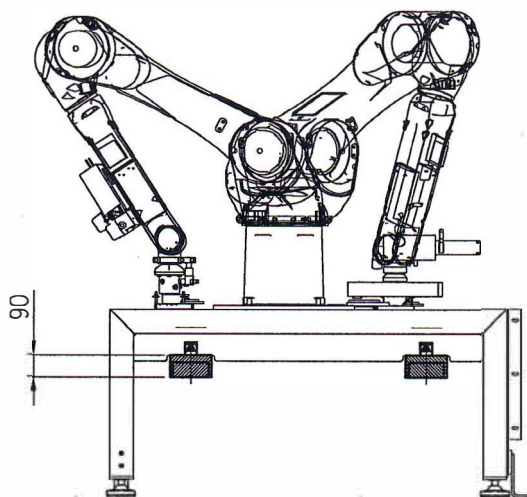
01

LINE
LIFTING SCHEME

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